COMP3000 – Project Portfolio

Computing Project

2022/2023



# 1 Acknowledgement

(Say thank you)

# 2 Abstract

Contents

[1 Acknowledgement 1](#_Toc120832398)

[2 Abstract 1](#_Toc120832399)

[3 Links 4](#_Toc120832400)

[4 Introduction 4](#_Toc120832401)

[4.1 Project Vision 4](#_Toc120832402)

[4.2 Background 4](#_Toc120832403)

[4.2.1 Infrastructure for the QTrobot 4](#_Toc120832404)

[4.3 Gantt Chart 4](#_Toc120832405)

[4.4 Poster 5](#_Toc120832406)

[5 Project Management 5](#_Toc120832407)

[5.1 User Stories 5](#_Toc120832408)

[5.2 Project Planning 5](#_Toc120832409)

[5.2.1 Trello Board 5](#_Toc120832410)

[5.2.2 Version Control 5](#_Toc120832411)

[5.2.3 Market Research 6](#_Toc120832412)

[5.2.3 Project Design 6](#_Toc120832413)

[5.3 Project Methodology 6](#_Toc120832414)

[5.4 Legal, Social, Ethical & Professional Issues 7](#_Toc120832415)

[5.4.1 Legal Issue 7](#_Toc120832416)

[5.4.2 Social Issue 7](#_Toc120832417)

[5.4.3 Ethical Issue 7](#_Toc120832418)

[5.4.4 Professional Issue 7](#_Toc120832419)

[5.5 Project Development 7](#_Toc120832420)

[5.6 Project Testing 7](#_Toc120832421)

[5.6.1 User Testing 7](#_Toc120832422)

[5.7 Meeting Minutes 7](#_Toc120832423)

[6 Sprint Reviews 8](#_Toc120832424)

[6.1 Sprint 0 8](#_Toc120832425)

[6.2 Sprint 1 9](#_Toc120832426)

[6.3 Sprint 2 9](#_Toc120832427)

[6.4 Sprint 3 10](#_Toc120832428)

[6.5 Sprint 4 10](#_Toc120832429)

[6.6 Sprint 5 10](#_Toc120832430)

[6.7 Sprint 6 10](#_Toc120832431)

[6.8 Sprint 7 10](#_Toc120832432)

[6.9 Sprint 8 10](#_Toc120832433)

[6.10 Sprint 9 10](#_Toc120832434)

[6.11 Sprint 10 10](#_Toc120832435)

[6.12 Sprint 11 10](#_Toc120832436)

[6.13 Sprint 12 10](#_Toc120832437)

[6.14 Sprint 13 10](#_Toc120832438)

[6.15 Sprint 14 10](#_Toc120832439)

[7 Critical Evaluation 10](#_Toc120832440)

[8 Evaluation (Discussion of Deviation, Big Changes) 10](#_Toc120832441)

[9 Conclusion 10](#_Toc120832442)

[10 References 10](#_Toc120832443)

[11 Appendix 10](#_Toc120832444)

# 3 Links

|  |  |
| --- | --- |
| **Document Reference** | **Online Links** |
| [Gantt Chart](#_Gantt_Chart) | [High Res Image (Imgur)](https://i.imgur.com/RVbzxjV.png), [(Mirror)](https://files.catbox.moe/5wyc0n.png) |
| [Trello Board](#_Trello_Board) | [Trello](https://trello.com/invite/b/stCxAKF8/bacc4ca9cf8aefa46403a2451d15e98f/comp3000computingproject) |
| [Version Control](#_Version_Control) | [GitHub](https://github.com/greatyarn/COMP3000_Computing_Project) |
| [Meeting Minutes](#_Meeting_Minutes) | [OneDrive](https://liveplymouthac-my.sharepoint.com/:w:/g/personal/gregory_kua_students_plymouth_ac_uk/ET_B3DV5e4NFkSzo-IntXoQB-lrf6EN-2o3SvNtGJFMPZQ?e=sp2L0p) |
| [Linux GUI Issue](#Linux_GUI_Issue) | [High Res Image (Imgur)](https://imgur.com/a/XXE2ADH) ([Mirror](https://files.catbox.moe/wo4iak.zip)) |
|  |  |
|  |  |

# 4 Introduction

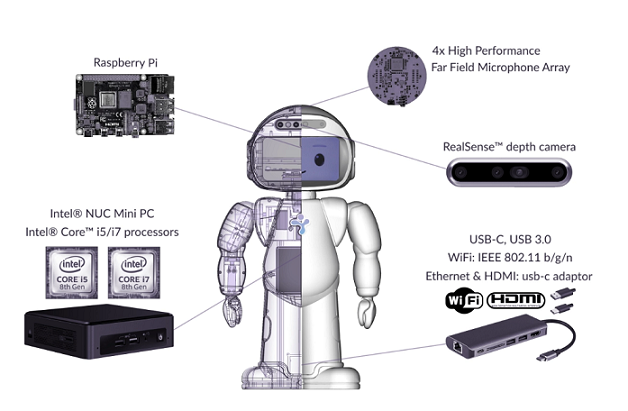
## 4.1 Project Vision

*The QTrobot is a toddler-like humanoid robot built by LuxAI. This project, Audio Authentication via Voice Recognition on QTrobot, or AAVR for short, is a software for patients who would like to allow for an easy way to authenticate themselves through robots with the use of their voice. This authentication process with the use of a human voice allows for patients to retrieve their medical records, which might contain their age, height, and weight. This method of authenticating by voice is safer and more convenient as it reduces the amount of human interaction that is needed, therefore allowing for an improvement of personal data security as a whole. With voice authentication, this allows for multiple different patient profiles to be set up conveniently.*

## 4.2 Background

(Background bout the project)

### 4.2.1 Infrastructure for the QTrobot



The QTrobot is an autism robot tutor for improving a child’s learning outcome at home (QTrobot, 2022). The documentation on the LuxAI website states that the robot is made off a raspberry pi, 4x microphones, a depth camera powered by Intel’s RealSense and a Nuc. The camera that is in the robot is connected to the Intel Nuc. The USB C adapter that is provided is also connected to the Nuc. The raspberry pi connects the rest of the components together. The Raspberry Pi links to the Nuc via an internal LAN (Local Area Network) cable. Each device, the nuc and the raspberry pi has been setup with different IP addresses. This component consists of the display that is on the face opf the robot, the speakers and microphone. There is also another usb at the back of the robot to plug in to the Raspberry Pi directly.

The QTRobot in the current configuration for this report is done via wifi through the Raspberry Pi. The Raspberry Pi passes the internet connection that is received through the LAN cable which is in the robot internally. This is how both the Raspberry Pi and the NUC can get an internet connection through one network.

## 4.3 Gantt Chart

(Intro explanation to the Gantt chart)

The gantt chart exists to allow for the project to be split between sections.

Chart, timeline, bar chart

Description automatically generated

## 4.4 Poster

The poster that can be seen below shows … /

(Poster to be inserted here)

# 5 Project Management

## 5.1 User Stories

## 5.2 Project Planning

### 5.2.1 Trello Board

(Talk about Trello board)

### 5.2.2 Version Control

(Why choose GitHub)

### 5.2.3 Market Research

### 5.2.3 Project Design

## 5.3 Project Methodology

Diagram

Description automatically generated

A picture containing text, sky, indoor, map

Description automatically generated

## 5.4 Legal, Social, Ethical & Professional Issues

### 5.4.1 Legal Issue

### 5.4.2 Social Issue

### 5.4.3 Ethical Issue

### 5.4.4 Professional Issue

## 5.5 Project Development

## 5.6 Project Testing

### 5.6.1 User Testing

## 5.7 Meeting Minutes

(Insert Meeting Minutes here)

# 6 Sprint Reviews

(Intro towards Sprints here)

## 6.1 Sprint 0

Graphical user interface, text, application, chat or text message

Description automatically generated

Sprint 0 runs from the 6th October till 20th October. The project initiation document (PID) was made that includes the title of the project, project vision, risks, Gantt chart. This initial document will be the basis for the whole project which shows where the project would head in the future and acts as a steppingstone. The GitHub Repository has also been made during this sprint. A Trello board has also been set up to allow for management of tasks and within Trello automations has been set up for automatic labelling.

## 6.2 Sprint 1

Graphical user interface, text, application, chat or text message

Description automatically generated

Sprint 1 runs from 20th October till 3rd November 2022. During this sprint the QTrobot was checked to make sure that it can turn on and off it’s microphone via the ROS service. The base code was pushed with a template. It was here where there was a Linux GUI issue which did not allow me to run the terminal or any system apps. (Images can be found in the Links section of this document) It was then fix within a week.

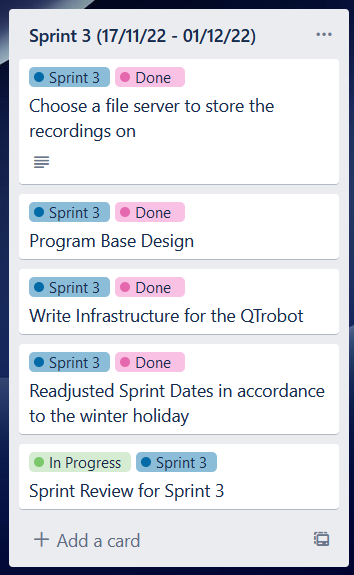
## 6.3 Sprint 2

Graphical user interface, text, application, chat or text message

Description automatically generated

Sprint 2 runs from the 3rd of November 2022 until the 17th November 2022. This sprint went into more research into Audio Recognition. Google’s speech recognition library and Amazon’s Rekognition was also checked accordingly to see which is more suitable for this project. Project Planning for the base designs for the enrolment phase and the recognition phase has been made using draw.io. The internet issue that has been persistent has been fixed during this time.

## 6.4 Sprint 3



Sprint 3 runs from 17th November 2022 until the 1st December 2022. This sprint consisted of a meeting with Dr Hooman from the University of Hertfordshire on the 18th November. This meeting consisted of

## 6.5 Sprint 4

## 6.6 Sprint 5

## 6.7 Sprint 6

## 6.8 Sprint 7

## 6.9 Sprint 8

## 6.10 Sprint 9

## 6.11 Sprint 10

## 6.12 Sprint 11

## 6.13 Sprint 12

## 6.14 Sprint 13

## 6.15 Sprint 14

# 7 Critical Evaluation

# 8 Evaluation (Discussion of Deviation, Big Changes)

# 9 Conclusion

# 10 References

https://luxai.com/robot-for-teaching-children-with-autism-at-home/

# 11 Appendix